

## 4 Sobolev spaces, trace theorem and normal derivative

Throughout,  $\Omega \subset \mathbf{R}^n$  will be a sufficiently smooth, bounded domain.

We use the standard Sobolev spaces

$$H^0(\mathbf{R}^n) := L_2(\mathbf{R}^n), \quad H^0(\Omega) := L_2(\Omega), \quad H^k(\mathbf{R}^n), \quad H^k(\Omega) \quad (k \text{ positive integer}).$$

Note that all these spaces are based on the use of weak derivatives up to order  $k$ . We will use the *Fourier transform* to redefine the norms in these spaces. Recall that the Fourier transform  $\mathcal{F}$  is defined by (there are different normalisations possible)

$$\hat{v}(\xi) := \mathcal{F}v(\xi) := \int_{\mathbf{R}^n} e^{-i2\pi\xi \cdot x} v(x) dx \quad (\xi \in \mathbf{R}^n).$$

Since

$$|\hat{v}(\xi)| = \left| \int_{\mathbf{R}^n} e^{-i2\pi\xi \cdot x} v(x) dx \right| \leq \int_{\mathbf{R}^n} |e^{-i2\pi\xi \cdot x} v(x)| dx = \int_{\mathbf{R}^n} |v(x)| dx$$

it follows that  $\hat{v}$  is well-defined whenever  $v \in L_1(\mathbf{R}^n)$ . The inversion formula for the Fourier transform is

$$\mathcal{F}^{-1}\hat{v}(x) := \int_{\mathbf{R}^n} e^{i2\pi\xi \cdot x} \hat{v}(\xi) d\xi.$$

One finds the following properties:

- If  $v, \hat{v} \in L_1(\mathbf{R}^n)$  then  $\mathcal{F}^{-1}\mathcal{F}v = v = \mathcal{F}\mathcal{F}^{-1}v$  wherever  $v$  is continuous.
- $\mathcal{F}$  generalises to a bounded linear mapping

$$\mathcal{F} : L_2(\mathbf{R}^n) \rightarrow L_2(\mathbf{R}^n)$$

and there holds

$$(\mathcal{F}\varphi, \mathcal{F}v) = (\varphi, v) = (\mathcal{F}^{-1}\varphi, \mathcal{F}^{-1}v) \quad \forall \varphi, v \in L_2(\mathbf{R}^n),$$

i.e.,  $\mathcal{F}$  is a unitary isomorphism. This property is known as *Plancherel's theorem*. The symbol  $(\cdot, \cdot)$  denotes the  $L_2$  inner product on  $\mathbf{R}^n$  and will be used throughout, also for its extension by duality. When referring to the inner product on a subset of  $\mathbf{R}^n$ , e.g. on  $\Omega$ , we add this subset as an index, e.g.  $(\cdot, \cdot)_\Omega$ .

- A conclusion from Plancherel's theorem is the relation

$$\|v\|_{L_2(\mathbf{R}^n)} = \|\hat{v}\|_{L_2(\mathbf{R}^n)} \quad \forall v \in L_2(\mathbf{R}^n).$$

**Example 4.1** Consider the one-dimensional case, i.e.,  $n = 1$ .

There holds  $\|v'\|_{L_2(\mathbf{R})} = \|\mathcal{F}(v')\|_{L_2(\mathbf{R})}$ , and for any  $v \in H^1(\mathbf{R})$  with compact support we obtain

$$\mathcal{F}(v')(\xi) = \int_{\mathbf{R}} e^{-i2\pi x \xi} v'(x) dx = v(x) e^{-i2\pi x \xi} \Big|_{x=-\infty}^{\infty} - \int_{\mathbf{R}} -i2\pi \xi e^{-i2\pi x \xi} v(x) dx = i2\pi \xi \hat{v}(\xi).$$

Therefore,

$$\|v'\|_{L_2(\mathbf{R})} = \|i2\pi\xi \hat{v}(\xi)\|_{L_2(\mathbf{R})} = 2\pi\|\xi \hat{v}(\xi)\|_{L_2(\mathbf{R})}$$

and

$$\|v\|_{H^1(\mathbf{R})}^2 = \|v\|_{L_2(\mathbf{R})}^2 + \|v'\|_{L_2(\mathbf{R})}^2 = \|\hat{v}\|_{L_2(\mathbf{R})}^2 + 4\pi^2\|\xi \hat{v}\|_{L_2(\mathbf{R})}^2 = \int_{\mathbf{R}} (1 + 4\pi^2\xi^2)|\hat{v}(\xi)|^2 d\xi,$$

so that

$$\|v\|_{H^1(\mathbf{R})} \quad \text{and} \quad \left( \int_{\mathbf{R}} (1 + \xi^2)|\hat{v}(\xi)|^2 d\xi \right)^{1/2} = \|(1 + |\xi|^2)^{1/2}\hat{v}\|_{L_2(\mathbf{R})}$$

are equivalent norms.

This example easily generalises to higher dimensions ( $n > 1$ ). Moreover, it leads us to the definition of Sobolev spaces on  $\mathbf{R}^n$  for any positive real order.

**Definition 4.1** For  $s > 0$  we define

$$H^s(\mathbf{R}^n) := \left\{ v \in L_2(\mathbf{R}^n); \|(1 + |\xi|^2)^{s/2}\hat{v}\|_{L_2(\mathbf{R}^n)} < \infty \right\}$$

with norm

$$\|v\|_{H^s(\mathbf{R}^n)} := \|(1 + |\xi|^2)^{s/2}\hat{v}\|_{L_2(\mathbf{R}^n)}.$$

As in Example 4.1 one sees that, for integer  $s$ , this norm is equivalent to the usual one (based on derivatives). For non-integer  $s$ ,  $H^s(\mathbf{R}^n)$  is called a *fractional order Sobolev space*.

We are now in a position to analyse the trace operator in the half-space case. Consider the situation given in Figure 4.1. For  $x = (x_1, \dots, x_n) \in \mathbf{R}^n$  we denote  $x' := (x_1, \dots, x_{n-1})$ . Then we define for  $v \in C_0^\infty(\mathbf{R}^n)$  its trace onto the hyperplane  $\mathbf{R}^{n-1} \times \{0\}$  by

$$\gamma_0 v(x') := v(x', x_n = 0), \quad x' \in \mathbf{R}^{n-1}.$$

**Theorem 4.1** (trace theorem, half-space case) For  $s > 1/2$  there exists a unique extension of  $\gamma_0$  to a bounded linear operator

$$\gamma_0 : H^s(\mathbf{R}^n) \rightarrow H^{s-1/2}(\mathbf{R}^{n-1}).$$

**Proof.** By density it suffices to consider  $v \in C_0^\infty(\mathbf{R}^n)$ . By the Fourier inversion formula we find that

$$\gamma_0 v(x') = \int_{\mathbf{R}^n} e^{i2\pi x \cdot \xi} \hat{v}(\xi) d\xi \Big|_{x_n=0} = \int_{\mathbf{R}^n} e^{i2\pi x' \cdot \xi'} \hat{v}(\xi) d\xi = \int_{\mathbf{R}^{n-1}} \left( \int_{\mathbf{R}} \hat{v}(\xi', \xi_n) d\xi_n \right) e^{i2\pi x' \cdot \xi'} d\xi'.$$

Therefore,

$$\mathcal{F}(\gamma_0 v)(\xi') = \int_{\mathbf{R}} \hat{v}(\xi', \xi_n) d\xi_n = \int_{\mathbf{R}} (1 + |\xi|^2)^{-s/2} (1 + |\xi|^2)^{s/2} \hat{v}(\xi', \xi_n) d\xi_n$$

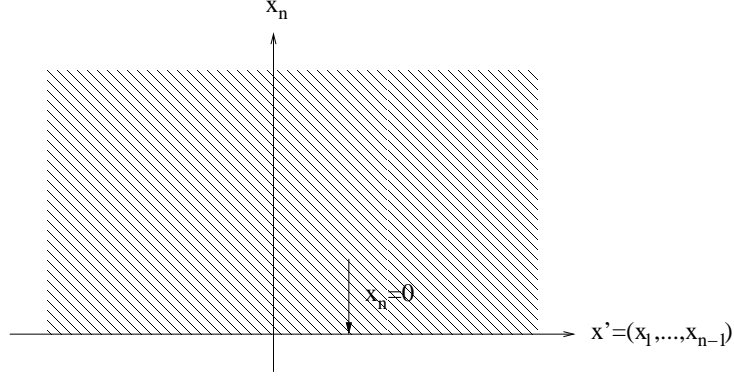


Figure 4.1: The trace in the half-space case.

and an application of the Cauchy-Schwarz inequality yields

$$|\mathcal{F}(\gamma_0 v)(\xi')|^2 \leq \int_{\mathbf{R}} (1 + |\xi|^2)^{-s} d\xi_n \int_{\mathbf{R}} (1 + |\xi|^2)^2 |\hat{v}(\xi', \xi_n)|^2 d\xi_n.$$

Now, by the substitution  $\xi_n = (1 + |\xi'|^2)^{1/2} t$ ,

$$\begin{aligned} M_s(\xi') &:= \int_{\mathbf{R}} (1 + |\xi|^2)^{-s} d\xi_n = \int_{\mathbf{R}} \frac{d\xi_n}{(1 + |\xi'|^2 + |\xi_n|^2)^s} \\ &= \frac{1}{(1 + |\xi'|^2)^{s-1/2}} \int_{\mathbf{R}} \frac{dt}{(1 + t^2)^s} < \infty \quad \text{iff } s > 1/2. \end{aligned}$$

Therefore, we can bound

$$(1 + |\xi'|^2)^{s-1/2} |\mathcal{F}(\gamma_0 v)(\xi')|^2 \leq C_s \int_{\mathbf{R}} (1 + |\xi|^2)^2 |\hat{v}(\xi)|^2 d\xi_n$$

for a constant  $C_s$  depending on  $s$ , and integration with respect to  $\xi'$  yields

$$\|\gamma_0 v\|_{H^{s-1/2}(\mathbf{R}^{n-1})} \leq C_s^{1/2} \|v\|_{H^s(\mathbf{R}^n)}.$$

□

So far we have dealt with Sobolev spaces on  $\mathbf{R}^n$ . For boundary value problems on Lipschitz domains this is obviously not enough.

**Definition 4.2** *Let  $\Omega \subset \mathbf{R}^n$  be a Lipschitz domain. For  $s \geq 0$  we introduce the following spaces:*

$$\begin{aligned} H^s(\Omega) &:= H^s(\mathbf{R}^n) \Big|_{\Omega} \quad \text{with norm } \|v\|_{H^s(\Omega)} := \inf_{V|_{\Omega}=v} \|V\|_{H^s(\mathbf{R}^n)}, \\ H_0^s(\Omega) &:= \overline{C_0^\infty(\Omega)}^{\|\cdot\|_{H^s(\Omega)}} \quad \text{with norm } \|\cdot\|_{H^s(\Omega)}, \end{aligned}$$

and

$$\tilde{H}^s(\Omega) := \{v \in H^s(\Omega); v^0 \in H^s(\mathbf{R}^n)\} \quad \text{with norm} \quad \|v\|_{\tilde{H}^s(\Omega)} := \|v^0\|_{H^s(\mathbf{R}^n)}$$

where  $v^0$  denotes the extension of  $v$  by 0 onto  $\mathbf{R}^n \setminus \Omega$ .

For  $s < 0$  we define

$$H^s(\Omega) := \left(\tilde{H}^{-s}(\Omega)\right)' \quad (\text{dual space}) \quad \text{with operator norm}$$

and

$$\tilde{H}^s(\Omega) := \left(H^{-s}(\Omega)\right)' \quad (\text{dual space}) \quad \text{with operator norm.}$$

**Remark 4.1** One can show that, for  $s > 0$ ,  $\tilde{H}^s(\Omega) = H_0^s(\Omega)$  if  $s \neq \text{integer} + 1/2$ . In the cases  $s = \text{integer} + 1/2$  the spaces are different,  $\tilde{H}^s(\Omega) \subset H_0^s(\Omega)$  in general.

Without going into the details, we mention that on a Lipschitz surface or boundary  $\Gamma$  all the above spaces can be defined analogously when  $|s| \leq 1$ . To this end one uses a partition of unity and local transformations onto subsets of  $\mathbf{R}^{n-1}$ . Higher order spaces require more regularity of  $\Gamma$ .

The trace theorem can be generalised to Lipschitz domains.

**Theorem 4.2** (trace theorem, general form)

Let  $\Omega \subset \mathbf{R}^n$  be a bounded Lipschitz domain with boundary  $\Gamma$ .

(i) For  $1/2 < s < 3/2$ ,  $\gamma_0$  has a unique extension to a bounded linear operator

$$\gamma_0 : H^s(\Omega) \rightarrow H^{s-1/2}(\Gamma).$$

(ii) For any  $s \in (1/2, 3/2)$  and any  $v \in H^{s-1/2}(\Gamma)$  there exists  $V := \mathcal{E}v \in H^s(\Omega)$  such that  $\gamma_0(V) = v$  and

$$\|\mathcal{E}v\|_{H^s(\Omega)} \leq C_s(\Omega) \|v\|_{H^{s-1/2}(\Gamma)} \quad \forall v \in H^{s-1/2}(\Gamma).$$

**Remark 4.2** Part (ii) of Theorem 4.2 means that  $\gamma_0$  has a right-inverse:

$$v = \gamma_0 V = \gamma_0 \mathcal{E}v$$

which is continuous, and that

$$\gamma_0 : H^s(\Omega) \rightarrow H^{s-1/2}(\Gamma)$$

is surjective, i.e.,  $\gamma_0\left(H^s(\Omega)\right) = H^{s-1/2}(\Gamma)$ . Of course, this right-inverse  $\mathcal{E}$  is an extension operator.

Having the trace operator at hand we can now make an interpretation of the Dirichlet boundary condition. Studying the Poisson equation with Dirichlet boundary condition

$$-\Delta u = f \quad \text{in } \Omega, \quad u|_{\Gamma} = g$$

we conclude two things. First, the equation  $u|_\Gamma = g$  means that  $\gamma_0 u = g$  in  $H^{1/2}(\Gamma)$  since the variational formulation of the Poisson equation is posed in  $H^1(\Omega)$  (subject to the Dirichlet condition). Second, the Dirichlet condition makes sense only for  $g \in H^{1/2}(\Gamma)$ . If  $g \notin H^{1/2}(\Gamma)$  then there does not exist a solution  $u \in H^1(\Omega)$  of the given boundary value problem. This is a conclusion of the surjectivity of the trace operator.

Besides the trace operator  $\gamma_0$ , in §1 we were concerned about the definition of the normal derivative  $\partial_n v$  of a function  $v \in H^1(\Omega)$ . We now deal with this operator.

The origin for the definition of the normal derivative is the first Green's formula, in the form

$$\int_{\Omega} -\Delta v w = \int_{\Omega} \nabla v \cdot \nabla w - \int_{\Gamma} \partial_n v w.$$

This leads us to the definition of  $\partial_n v$  for  $v \in H^1(\Omega)$  by

$$\langle \partial_n v, w \rangle_{\Gamma} := \int_{\Omega} \nabla v \cdot \nabla W + \int_{\Omega} \Delta v W$$

where  $W \in H^1(\Omega)$  is any extension of  $w \in H^{1/2}(\Gamma)$ . The notation  $\langle \Phi, \varphi \rangle_{\Gamma}$  means the application of the functional  $\Phi$  to  $\varphi$  defined on  $\Gamma$ , in this case it is the duality between  $H^{-1/2}(\Gamma)$  and  $H^{1/2}(\Gamma)$ . For  $\Phi, \varphi \in L_2(\Gamma)$  it is simply the  $L_2(\Gamma)$ -inner product between  $\Phi$  and  $\varphi$ .

**Lemma 4.1**

$$\partial_n : \{v \in H^1(\Omega); \Delta v \in \tilde{H}^{-1}(\Omega)\} \rightarrow H^{-1/2}(\Gamma)$$

is well-defined and continuous when defining

$$\int_{\Omega} \Delta v W := (\Delta v, W)_{\Omega}$$

as duality between  $\tilde{H}^{-1}(\Omega)$  and  $H^1(\Omega)$ .

**Proof.** (i) First we show that the definition of  $\langle \partial_n v, w \rangle_{\Gamma}$  is independent of the extension  $W$  of  $w$ . Let  $W_1, W_2 \in H^1(\Omega)$  be two extensions of  $w$ , i.e.,  $\gamma_0 W_1 = \gamma_0 W_2 = w$ . Then

$$\int_{\Omega} \nabla v \cdot \nabla (W_1 - W_2) + \int_{\Omega} \Delta v (W_1 - W_2) = 0$$

by the second Green identity since  $W_1 - W_2 \in H_0^1(\Omega)$ . This proves that  $\langle \partial_n v, \gamma_0 (W_1 - W_2) \rangle_{\Gamma} = 0$  as wanted.

(ii) Now we show the boundedness of  $\partial_n$ . Let  $\mathcal{E} : H^{1/2}(\Gamma) \rightarrow H^1(\Omega)$  denote the extension

operator from Theorem 4.2(ii). We estimate

$$\begin{aligned}
\|\partial_n v\|_{H^{-1/2}(\Gamma)} &= \sup_{w \in H^{1/2}(\Gamma) \setminus \{0\}} \frac{\langle \partial_n v, w \rangle_\Gamma}{\|w\|_{H^{1/2}(\Gamma)}} \leq C \sup_{w \in H^{1/2}(\Gamma) \setminus \{0\}} \frac{\langle \partial_n v, w \rangle_\Gamma}{\|\mathcal{E}w\|_{H^1(\Omega)}} \\
&= C \sup_{w \in H^{1/2}(\Gamma) \setminus \{0\}} \frac{\int_\Omega \nabla v \cdot \nabla \mathcal{E}w + \int_\Omega \Delta v \mathcal{E}w}{\|\mathcal{E}w\|_{H^1(\Omega)}} \leq C \sup_{W \in H^1(\Omega) \setminus \{0\}} \frac{\int_\Omega \nabla v \cdot \nabla W + \int_\Omega \Delta v W}{\|W\|_{H^1(\Omega)}} \\
&\leq C \sup_{W \in H^1(\Omega) \setminus \{0\}} \frac{\|v\|_{H^1(\Omega)} \|W\|_{H^1(\Omega)} + \|\Delta v\|_{\tilde{H}^{-1}(\Omega)} \|W\|_{H^1(\Omega)}}{\|W\|_{H^1(\Omega)}} \\
&= C (\|v\|_{H^1(\Omega)} + \|\Delta v\|_{\tilde{H}^{-1}(\Omega)}).
\end{aligned}$$

□

**Remark 4.3**  $\Delta v \in L_2(\Omega)$  implies  $\Delta v \in \tilde{H}^{-1}(\Omega)$ .